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# P10 Pro Datasheet

#### **Product Overview**

The P10 Pro is a high flow servo proportional valve engineered for demanding heavy duty applications. With strong dynamic stability and robust construction, it manages large volumes of hydraulic power with confidence, supporting presses, power and energy systems, and large-scale industrial automation. It is designed for environments where consistent control under higher loads is essential.

#### **Key Features**

- Onboard electronics with spool position feedback
- Rated flow of up to 160 I/min (at 70 Bar  $\Delta P$ )
- · Based on the NG10 port pattern
- Bandwidth > 65 Hz (-3 dB, up to  $\pm 25\%$  FS)
- Chip shear capability of > 700 N
- Valve mass of 4 kg

#### Customisation

The P10 Pro is designed to be customised. Standard modifications include:

- · Rated flow rates of up to 160 I/min
- Multiple voltage or current control options
- · Various seal materials available
- Non-standard configurations available

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#### Contact Us

If you have any questions about using the P10 Pro, or if you need a non-standard configuration, we would be happy to hear from you.

Contact us using the details below and one of our team will be there to assist you.

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# **Technical Data**

#### General Data

Design		Direct Drive Servo Proportional Valve
Actuation		Rotary-Linear
Size		NG10
Mounting Interface		ISO 4401-05-04
Ambient Temperature	°C (°F)	-20 to +60 (-4 to +140)
Mass	kg (lb)	4 (8.8)
Vibration Resistance (1)	g	30
Shock Resistance (2)	g	50

#### Hydraulic Data

Max. Operating Pressure (P, A, B)	Bar (psi)	350 (5,000)
Max. Operating Pressure (T)	Bar (psi)	250 (3,600)
Fluid		Hydraulic Oil DIN 51524
Fluid Temperature	°C (°F)	-20 to +80 (-5 to +175)
Filtration		ISO 4406 (1999) 18/16/13
Viscosity	cSt	5 to 500
Rated Flow (3)	l/min (gpm)	40 to 160 (10.6 to 42)
Flow Maximum	I/min (gpm)	250 (66)
Pressure Gain	%/%	> 40
Leakage at 100 bar	I/min (gpm)	< 1 (0.4)

#### Static/Dynamic Data

Response Time at 100% Step Input (4)	ms	< 20
Frequency Response (4) (-3dB gain, ±25% signal)	Hz	> 65
Frequency Response <sup>(4)</sup> (-90deg phase, ±25% signal)	Hz	> 65
Hysteresis	%	< 0.2
Threshold	%	< 0.1
Null Shift	%	< 1

<sup>1.</sup>BS EN 60068-2 (20-35 Hz, 16 g for 15 minutes per axis, 35-2000 Hz, 35 g for 15 minutes per axis).

<sup>2.</sup>BS EN 60068-2 (20 shocks 50 g in Z axis).

<sup>3.</sup> Rated at a  $\Delta P$  of 70 bar (35 bar per edge), 160 l/min only available for Axis cut valves.

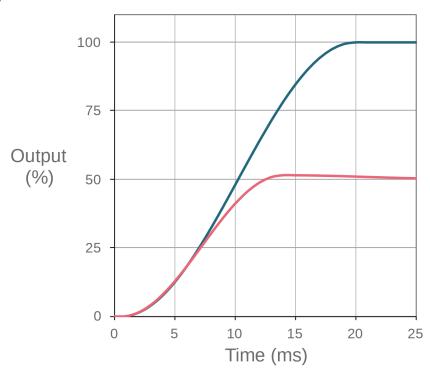
<sup>4.</sup> Measured as 90% output rise time with  $\Delta 70$  bar P-T (two control edges).



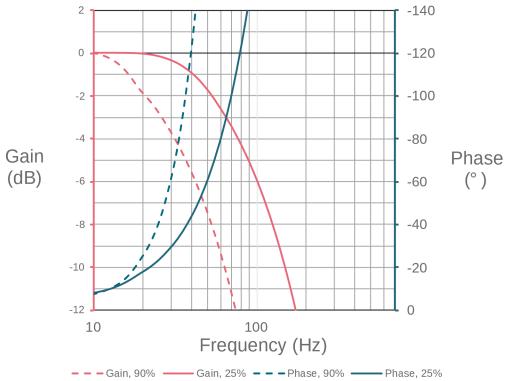


# Performance Graphs

Step Response (1)







<sup>1.</sup> Measured at a 70 bar pressure drop.



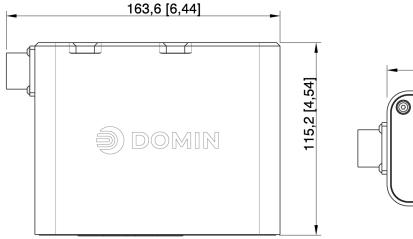


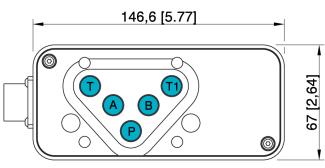
# Standards References

EMC Regulations:	immunity: EN 61000-6-2, Emission: EN 61000-6-3
Performance Tests:	ISO 10770-1
Pressure Rating:	ISO 10771

Hydraulic Interface: ISO 4401-05-04

# **Unit Dimensions**





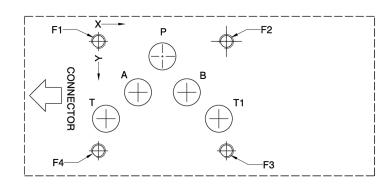
Nominal dimensions are displayed in mm. Not to scale.





# Mounting Dimensions

		Р	Α	В	Т	T1	X1 <sup>(1)</sup>	Y1 <sup>(1)</sup>	F1	F2	F3	F4
Diameter Ø	mm	11.2	11.2	11.2	11.2	11.2	6.3	6.3	М6	M6	M6	M6
X Position	mm	27	16.7	37.3	3.2	50.8	-8.0	62.0	0	54	54	0
Y Position	mm	6.3	21.4	21.4	32.5	32.5	11	11	0	0	46	46



# Bolts (F1, F2, F3, F4)

Type: M6 x 120 DIN EN ISO 4762-10.9

Required Torque: 13 Nm

## O-Rings (P, A, B, T, T1, X°, Y°)

Type: 5x ISO 3601-1-014 Type: 2x ISO 3601-1-011

# **LED Status**

LED Colour	LED State	Motor Drive State	Valve State
Green	Solid - On	Motor Drive On	Valve OK
	Flashing	Motor Drive On	Warning Present
Red	Solid - On	Motor Drive Off	Valve OK
neu	Flashing	Motor Drive Off	Error Present

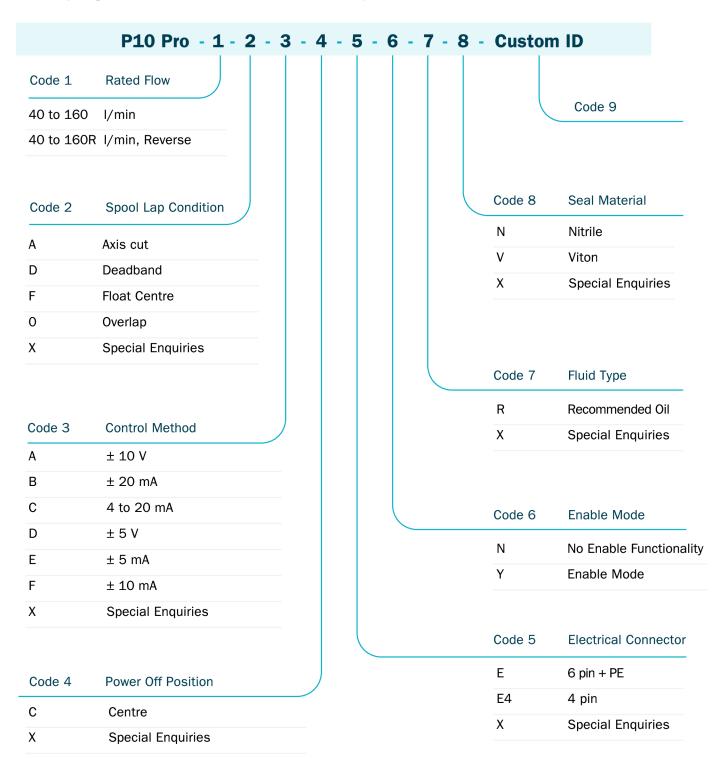
<sup>1.</sup> Valve includes seal grooves for X and Y ports for installation in existing systems – X and Y connections are NOT required for valve operation. Port X & Y not in use, seals are for blanking only.





# SKU Selection

Use our SKU builder to configure your Domin Valve. If you need a non-standard setup or a bespoke option, just get in touch – we can tailor a solution to suit your exact requirements.







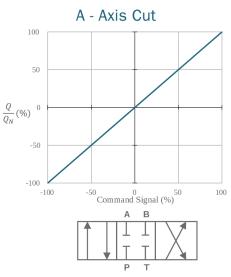
### Code 1 Rated Flow

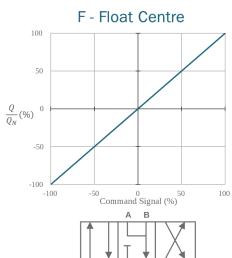
Any value in range 40 to 160 LPM rated at 35 bar  $\Delta P$  per control edge. R – Suffix for reversal of A and B port e.g. 160R

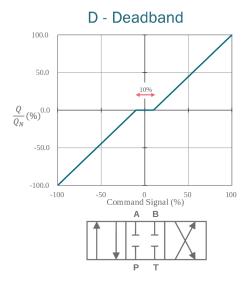
# Code 2 Lap Condition

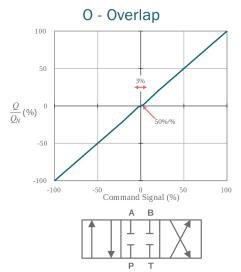
	Overlap Region (%)	Flow Gradient (%/%)	
A Axis Cut	0	100	1% mechanical overlap, linearised
D Deadband	±10	0	10% mechanical overlap, 10% flow dead band
F Float Centre	0	100	3% overlap P, 3% underlap T, linearised
O Overlap	±3	50	3% mechanical overlap, linearised to 50% gain over centre

X For other options please enquire













### Code 3 Control Methods

Code	Input Signal	Input Impedance	Output Signal	Output Load Impedance	
Α	± 10 V	200 kΩ	± 10.5 V	_	
D	± 5 V	200 N22	± 5.25 V		
E	± 5 mA	402 Ω	± 5.25 mA		
F	± 10 mA		± 10.5 mA	600 Ω	
В	± 20 mA		± 21 mA		
C <sup>(1)</sup>	4 to 20 mA		3.8 to 21 mA	600 Ω	
Χ	For other options please enquire				

<sup>1.</sup> For 4 to 20 mA input signal, a current input below 2 mA will disable the motor drive

#### Electrical

Supply Voltage (Operational)	V	22 to 30
Supply Voltage (Absolute) (1)	V	-0.5 to 33
Current Consumption (2)	Α	0.8
Peak Current Draw (3)	Α	8

<sup>1.</sup> Conditions outside the absolute maximum ratings may cause permanent damage to the valve. These are absolute ratings only. Operation of the product outside of the nominal operating conditions is not guaranteed and may affect product reliability

### Code 4 Power Off Position

С	Centre. The spool is intended to return to centre passively under typical flow conditions.
Χ	For other options please enquire

<sup>2.</sup> Valves with a current command signal use a 0.1% tolerance shunt resistor to measure demand current.

<sup>3.</sup> For differing input and output signals, use two letters, e.g. AC denotes  $\pm$  10 V Input and 4 to 20 mA output

<sup>2.</sup> Approximate current consumption for 100 Hz at 25 % amplitude

 $<sup>{\</sup>tt 3. The\ valve\ supply\ must\ be\ protected\ with\ a\ 10\ AT\ fuse\ or\ equivalent\ overcurrent\ protection\ device}$ 

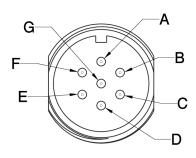




### Code 5 Electrical Connectors

#### 6 + PE Circular Connector (E)

Type:	Case-Mounted
Termination:	Connector according to EN 175201-804/MIL 5015 equivalent, shell size 14
Number of Contacts:	7

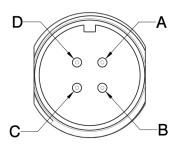


Pin	Function	Description
Α	Supply +	+24 V
В	Supply 0 V	0 V
C (1)	Output – Enable input	Output 0 V Reference Drive enable input
D	Input +	Differential input signal, +
E	Input –	Differential input signal, –
F	Output +	Output signal
G	Earth	-

<sup>1.</sup> When the enable function is selected, the function of pin C is the enable input. This replaces the standard pin function.

### 4 Pin Circular Connector (E4)

Type:	Case-Mounted
Termination:	Connector according to EN 175201-804/MIL 5015 equivalent, shell size 14
Number of Contacts:	4



Pin	Function	Description
Α	Supply +	+24 V
В	Input +	Differential input signal, +
С	Input –	Differential input signal, -
D	Supply 0 V	0 V





### Code 6 Enable Modes

Valves can be provided with an enable function. This allows the valve to be enabled or disabled by varying the voltage into the enable pin. Note that valves with a code C command type can also be enabled or disabled using the command signal; see the corresponding table above for further details. Enable function is only applicable with Code E electrical connector option.

N	No Enable Functionality
Υ	Enable Mode

Normal Operating Condition	S	Units	Min.	Typical	Max.
	Drive On	٧	9	-	30
Enable Mode	Drive Off	V	0	-	5
	Input Impedance	kΩ	-	15	-

## Code 7 Fluid Types

R	Recommended - any hydraulic oil in accordance with DIN 51524, filtered in accordance with ISO4406 18/16/13. Compatibility with water-free synthetic fluids available on enquiry.
X	For other options please enquire

### Code 8 Seal Materials

N	Nitrile (Shore 90)
V	Viton (Shore 85)
X	For other options please enquire